

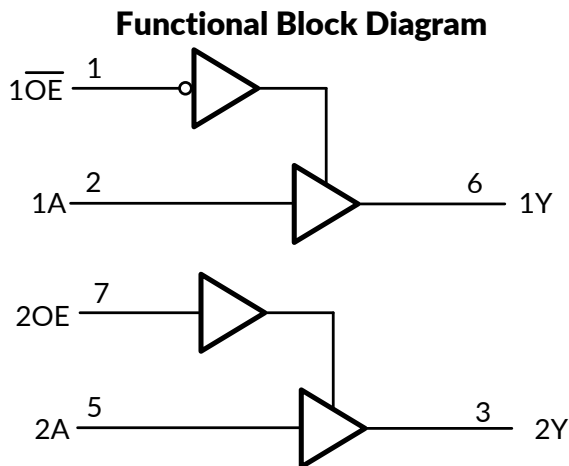
# RS2G241 Dual Buffer and Driver With 3-State Outputs

## 1 FEATURES

- **Operating Voltage Range: 1.65V to 5.5V**
- **Low Power Consumption: 1 $\mu$ A (Max)**
- **Operating Temperature Range: -40 $^{\circ}$ C to +125 $^{\circ}$ C**
- **Input Accept Voltage to 5.5V**
- **High Output Drive:  $\pm$ 24mA at  $V_{CC}=3.0V$**
- **I<sub>off</sub> Supports Partial-Power-Down Mode Operation**
- **Micro Size Packages: MSOP8, VSSOP8**

## 2 APPLICATIONS

- **AC Receiver**
- **Blu-ray Players and Home Theaters**
- **Desktops or Notebook PCs**
- **Digital Video Cameras (DVC)**
- **Mobile Phones**
- **Personal Navigation Device (GPS)**
- **Portable Media Player**



## 3 DESCRIPTIONS

This dual buffer and line driver is designed for 1.65V to 5.5V  $V_{CC}$  operation.

The RS2G241 device is designed specifically to improve both the performance and density of 3-state memory-address drivers, clock drivers, and bus-oriented receivers and transmitters.

The RS2G241 device is organized as two 1bit line drivers with separate output-enable (1  $\overline{OE}$ , 2OE) inputs. When 1 $\overline{OE}$  is low and 2OE is high, the device passes data from the A inputs to the Y outputs. When 1 $\overline{OE}$  is high and 2OE is low, the outputs are in the high-impedance state.

To ensure the high-impedance state during power up or power down,  $\overline{OE}$  should be tied to  $V_{CC}$  through a pullup resistor, and OE should be tied to GND through a pulldown resistor; the minimum value of the resistor is determined by the current-sinking or the current-sourcing capability of the driver.

This device is fully specified for partial-power-down applications using I<sub>off</sub>. The I<sub>off</sub> circuitry disables the outputs, preventing damaging current backflow through the device when it is powered down.

**Device Information <sup>(1)</sup>**

PART NUMBER	PACKAGE	BODY SIZE (NOM)
RS2G241	MSOP8	3.00mm $\times$ 3.00mm
	VSSOP8	2.00mm $\times$ 2.30mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

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## 4 REVISION HISTORY

Note: Page numbers for previous revisions may differ from page numbers in the current version.

Version	Change Date	Change Item
A.1	2023/07/06	Initial version completed
A.1.1	2024/02/29	Modify packaging naming
A.2	2024/04/22	Update font

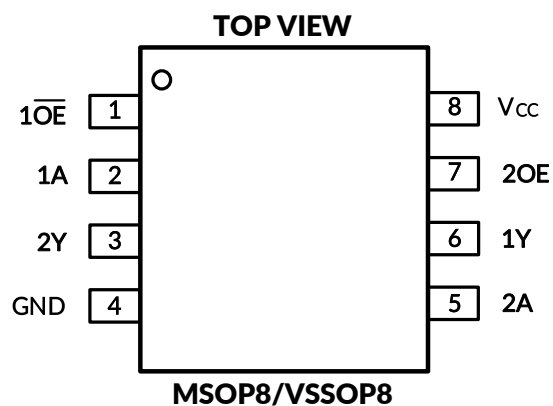
**5 PACKAGE/ORDERING INFORMATION <sup>(1)</sup>**

PRODUCT	ORDERING NUMBER	TEMPERATURE RANGE	PACKAGE LEAD	PACKAGE MARKING <sup>(2)</sup>	MSL <sup>(3)</sup>	PACKAGE OPTION
RS2G241	RS2G241XM	-40°C ~+125°C	MSOP8	RS2G241	MSL3	Tape and Reel, 4000
	RS2G241XVS8	-40°C ~+125°C	VSSOP8	2241	MSL3	Tape and Reel, 3000

## NOTE:

- (1) This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the right-hand navigation.
- (2) There may be additional marking, which relates to the lot trace code information (data code and vendor code), the logo or the environmental category on the device.
- (3) MSL, The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications.

## 6 PIN CONFIGURATIONS



### PIN DESCRIPTION

PIN	NAME	TYPE <sup>(1)</sup>	FUNCTION
MSOP8/VSSOP8			
1	$\overline{1OE}$	I	Output enable (Active low)
2	1A	I	Input
3	2Y	O	Output
4	GND	-	Ground.
5	2A	I	Input
6	1Y	O	Output
7	2OE	I	Output enable (Active high)
8	V <sub>CC</sub>	P	Power pin

(1) I=input, O=output, P=power.

## 7 SPECIFICATIONS

### 7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted) <sup>(1) (2)</sup>

		MIN	MAX	UNIT
V <sub>CC</sub>	Supply voltage range	-0.5	6.5	V
V <sub>I</sub>	Input voltage range <sup>(2)</sup>	-0.5	6.5	V
V <sub>O</sub>	Voltage range applied to any output in the high-impedance or power-off state <sup>(2)</sup>	-0.5	6.5	V
V <sub>O</sub>	Voltage range applied to any output in the high or low state <sup>(2) (3)</sup>	-0.5	V <sub>CC</sub> +0.5	V
I <sub>IK</sub>	Input clamp current	V <sub>I</sub> <0	-50	mA
I <sub>OK</sub>	Output clamp current	V <sub>O</sub> <0	-50	mA
I <sub>O</sub>	Continuous output current		±50	mA
	Continuous current through V <sub>CC</sub> or GND		±100	mA
θ <sub>JA</sub>	Package thermal impedance <sup>(4)</sup>	MSOP8	170	°C/W
		VSSOP8	205	K/W
T <sub>J</sub>	Junction temperature <sup>(5)</sup>	-65	150	°C
T <sub>stg</sub>	Storage temperature	-65	150	°C

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) The input and output negative-voltage ratings may be exceeded if the input and output current ratings are observed.

(3) The value of V<sub>CC</sub> is provided in the Recommended Operating Conditions table.

(4) The package thermal impedance is calculated in accordance with JESD-51.

(5) The maximum power dissipation is a function of T<sub>J(MAX)</sub>, R<sub>θJA</sub>, and T<sub>A</sub>. The maximum allowable power dissipation at any ambient temperature is P<sub>D</sub> = (T<sub>J(MAX)</sub> - T<sub>A</sub>) / R<sub>θJA</sub>. All numbers apply for packages soldered directly onto a PCB.

### 7.2 ESD Ratings

The following ESD information is provided for handling of ESD-sensitive devices in an ESD protected area only.

		VALUE	UNIT
V <sub>(ESD)</sub> Electrostatic discharge	Human-Body Model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±2000	V
	Charged-Device Model (CDM), per ANSI/ESDA/JEDEC JS-002 <sup>(2)</sup>	±1000	V
	Machine Model (MM)	±200	V

(1) JEDEC document JEP155 states that 500 V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250 V CDM allows safe manufacturing with a standard ESD control process.



#### ESD SENSITIVITY CAUTION

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

## 8 ELECTRICAL CHARACTERISTICS

over recommended operating free-air temperature range (Full=-40°C to +125°C, typical values are at  $T_A = +25^\circ\text{C}$ , unless otherwise noted.)<sup>(1)</sup>

### 8.1 Recommended Operating Conditions

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	MAX	UNIT
Supply Voltage	$V_{CC}$	Operating	1.65	5.5	V
		Data retention only	1.5		
High-Level Input Voltage	$V_{IH}$	$V_{CC}=1.65\text{V to }1.95\text{V}$	$0.65 \times V_{CC}$		V
		$V_{CC}=2.3\text{V to }2.7\text{V}$	1.7		
		$V_{CC}=3\text{V to }3.6\text{V}$	2		
		$V_{CC}=4.5\text{V to }5.5\text{V}$	$0.7 \times V_{CC}$		
Low-Level Input Voltage	$V_{IL}$	$V_{CC}=1.65\text{V to }1.95\text{V}$		$0.35 \times V_{CC}$	V
		$V_{CC}=2.3\text{V to }2.7\text{V}$		0.7	
		$V_{CC}=3\text{V to }3.6\text{V}$		0.8	
		$V_{CC}=4.5\text{V to }5.5\text{V}$		$0.3 \times V_{CC}$	
Input Voltage	$V_I$		0	5.5	V
Output Voltage	$V_O$		0	$V_{CC}$	V
Input Transition Rise or Fall	$\Delta t/\Delta v$	$V_{CC}=1.8\text{V} \pm 0.15\text{V}, 2.5\text{V} \pm 0.2\text{V}$		20	ns/V
		$V_{CC}=3.3\text{V} \pm 0.3\text{V}$		10	
		$V_{CC}=5\text{V} \pm 0.5\text{V}$		5	
Operating Temperature	$T_A$		-40	125	°C

(1) All unused inputs of the device must be held at  $V_{CC}$  or GND to ensure proper device operation.

## 8.2 DC Characteristics

PARAMETER		TEST CONDITIONS	V <sub>CC</sub>	TEMP	MIN <sup>(2)</sup>	TYP <sup>(3)</sup>	MAX <sup>(2)</sup>	UNIT
V <sub>OH</sub>		I <sub>OH</sub> = -100μA	1.65V to 5.5V	Full	V <sub>CC</sub> -0.1			V
		I <sub>OH</sub> = -4mA	1.65V		1.2			
		I <sub>OH</sub> = -8mA	2.3V		1.9			
		I <sub>OH</sub> = -16mA	3V		2.4			
		I <sub>OH</sub> = -24mA			2.3			
		I <sub>OH</sub> = -32mA	4.5V		3.8			
V <sub>OL</sub>		I <sub>OL</sub> = 100μA	1.65V to 5.5V	Full			0.1	V
		I <sub>OL</sub> = 4mA	1.65V				0.45	
		I <sub>OL</sub> = 8mA	2.3V				0.3	
		I <sub>OL</sub> = 16mA	3V				0.4	
		I <sub>OL</sub> = 24mA					0.55	
		I <sub>OL</sub> = 32mA	4.5V				0.55	
I <sub>I</sub>	A or $\overline{OE}$ input	V <sub>I</sub> =5.5V or GND	0V to 5.5V	+25°C		±0.1	±1	μA
				Full			±5	
I <sub>off</sub>		V <sub>I</sub> or V <sub>O</sub> =5.5V	0	+25°C		±0.1	±1	μA
				Full			±10	
I <sub>CC</sub>		V <sub>I</sub> =5.5V or GND, I <sub>O</sub> =0	1.65V to 5.5V	+25°C		0.1	1	μA
				Full			10	
ΔI <sub>CC</sub>		One input at V <sub>CC</sub> -0.6V, Other inputs at V <sub>CC</sub> or GND	3V to 5.5V	Full			500	μA
Input Capacitance (C <sub>i</sub> )		V <sub>I</sub> =V <sub>CC</sub> or GND	3.3V	+25°C		4		pF

(1) All unused inputs of the device must be held at V<sub>CC</sub> or GND to ensure proper device operation.

(2) Limits are 100% production tested at 25°C. Limits over the operating temperature range are ensured through correlations using statistical quality control (SQC) method.

(3) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration.



### 8.3 Switching Characteristics, $C_L=15\text{pF}$

over recommended operating free-air temperature range (-40°C to 125°C, unless otherwise noted.)<sup>(1)</sup>

PARAMETER	FROM (INPUT)	TO (OUTPUT)	$V_{CC}=1.8\text{V}\pm 0.15\text{V}$	$V_{CC}=2.5\text{V}\pm 0.2\text{V}$	$V_{CC}=3.3\text{V}\pm 0.3\text{V}$	$V_{CC}=5\text{V}\pm 0.5\text{V}$	UNIT
			TYP	TYP	TYP	TYP	
$t_{pd}$	A	Y	6.5	4.0	4.2	2.2	ns

### 8.4 Switching Characteristics, $C_L=30\text{pF}$ or $50\text{pF}$

over recommended operating free-air temperature range (-40°C to 125°C, unless otherwise noted.)<sup>(1)</sup>

PARAMETER	FROM (INPUT)	TO (OUTPUT)	$V_{CC}=1.8\text{V}\pm 0.15\text{V}$	$V_{CC}=2.5\text{V}\pm 0.2\text{V}$	$V_{CC}=3.3\text{V}\pm 0.3\text{V}$	$V_{CC}=5\text{V}\pm 0.5\text{V}$	UNIT
			TYP	TYP	TYP	TYP	
$t_{pd}$	A	Y	8.9	5.5	4.3	3.1	ns
$t_{en}$	$\overline{OE}$	Y	9.8	6.0	5.4	3.5	ns
$t_{dis}$	$\overline{OE}$	Y	7.7	4.6	4.6	3.3	ns

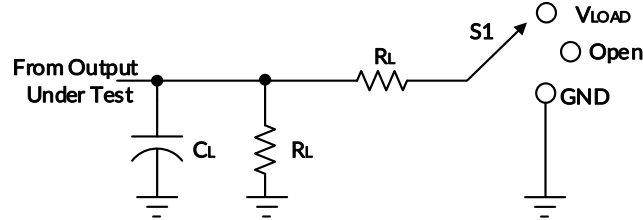
### 8.5 Operating Characteristics

$T_A=25^\circ\text{C}$

PARAMETER			TEST CONDITIONS	$V_{CC}=1.8\text{V}$	$V_{CC}=2.5\text{V}$	$V_{CC}=3.3\text{V}$	$V_{CC}=5\text{V}$	UNIT
				TYP	TYP	TYP	TYP	
$C_{pd}$	Power Dissipation Capacitance	Output Enabled	f=10MHz	18	18	19	21	pF
		Output Disabled		2	2	2	4	

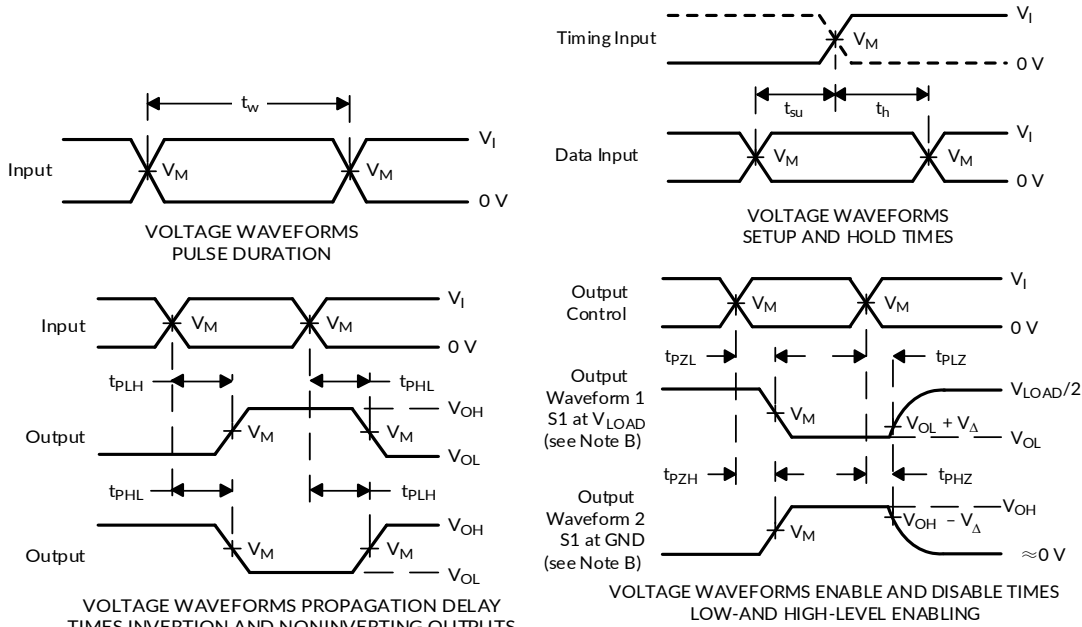
(1) All unused inputs of the device must be held at  $V_{CC}$  or GND to ensure proper device operation.

## 9 PARAMETER MEASUREMENT INFORMATION



TEST	S1
$t_{PLH}/t_{PHL}$	Open
$t_{PLZ}/t_{PZL}$	$V_{LOAD}$
$t_{PHZ}/t_{PZH}$	GND

$V_{CC}$	INPUTS		$V_M$	$V_{LOAD}$	$C_L$		$R_L$		$V_{\Delta}$
	$V_I$	$t_r/t_f$							
$1.8V \pm 0.15V$	$V_{CC}$	$\leq 2ns$	$V_{CC}/2$	$2 \times V_{CC}$	15pF	30pF	1M $\Omega$	1k $\Omega$	0.15V
$2.5V \pm 0.2V$	$V_{CC}$	$\leq 2ns$	$V_{CC}/2$	$2 \times V_{CC}$	15pF	30pF	1M $\Omega$	500 $\Omega$	0.15V
$3.3V \pm 0.3V$	3V	$\leq 2.5ns$	1.5V	6V	15pF	50pF	1M $\Omega$	500 $\Omega$	0.3V
$5V \pm 0.5V$	$V_{CC}$	$\leq 2.5ns$	$V_{CC}/2$	$2 \times V_{CC}$	15pF	50pF	1M $\Omega$	500 $\Omega$	0.3V



NOTES: A.  $C_L$  includes probe and jig capacitance.

B. Waveform 1 is for an output with internal conditions such that the output is low, except when disabled by the output control.

Waveform 2 is for an output with internal conditions such that the output is high, except when disabled by the output control.

C. All input pulses are supplied by generators having the following characteristics:  $PRR \leq 10$  MHz,  $Z_o = 50 \Omega$ .

D. The outputs are measured one at a time, with one transition per measurement.

E.  $t_{PLZ}$  and  $t_{PHZ}$  are the same as  $t_{dis}$ .

F.  $t_{PZL}$  and  $t_{PZH}$  are the same as  $t_{en}$ .

G.  $t_{PLH}$  and  $t_{PHL}$  are the same as  $t_{pd}$ .

H. All parameters and waveforms are not applicable to all devices.

**Figure 1. Load Circuit and Voltage Waveforms**

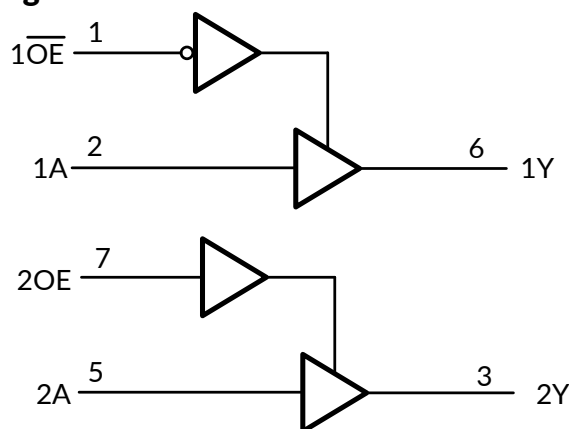
## 10 DETAILED DESCRIPTION

### 10.1 Overview

The RS2G241 device is designed specifically to improve both the performance and density of 3-state memory-address drivers, clock drivers, and bus-oriented receivers and transmitters. The RS2G241 device is organized as two 1-bit line drivers with separate output-enable ( $\overline{1OE}$ , 2OE) inputs. When  $\overline{1OE}$  is low and 2OE is high, the device passes data from the A inputs to the Y outputs. When  $\overline{1OE}$  is high and 2OE is low, the outputs are in the high-impedance state.

The RS2G241 is also an effective redriver, with a maximum output current drive of 32 mA.

### 10.2 Functional Block Diagram



**Figure 2. Logic Diagram (Positive Logic)**

### 10.3 Feature Description

To ensure the high-impedance state during power up or power down,  $\overline{OE}$  should be tied to  $V_{CC}$  through a pullup resistor, and OE should be tied to GND through a pulldown resistor; the minimum value of the resistor is determined by the current-sinking or the current-sourcing capability of the driver.

This device is fully specified for partial-power-down applications using  $I_{off}$ . The  $I_{off}$  circuitry disables the outputs, preventing damaging current backflow through the device when it is powered down.

### 10.4 Device Functional Modes

Table 1 and Table 2 list the functional modes of the RS2G241.

**Table 1. Gate 1 Functional Table**

INPUTS		OUTPUT
$\overline{1OE}$	1A	1Y
L	H	H
L	L	L
H	X	Z

**Table 2. Gate 2 Functional Table**

INPUTS		OUTPUT
2OE	2A	2Y
H	H	H
H	L	L
L	X	Z

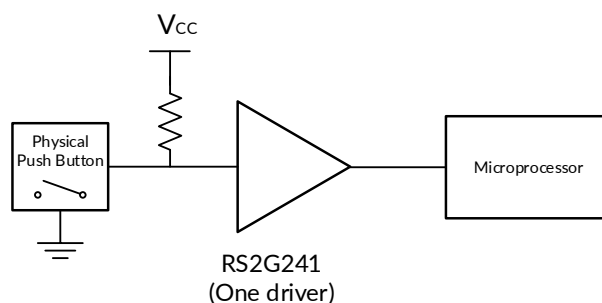
## 11 APPLICATION AND IMPLEMENTATION

Information in the following applications sections is not part of the Runic component specification, and Runic does not warrant its accuracy or completeness. Runic's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

### 11.1 Application Information

Typical Application shows a simple application where a physical push button is connected to the RS2G241. The push button is in a physical location far enough away from the processor that the input signal is weak and needs to be redriven. The RS2G241 acts as a redriver, providing a strong input signal to the processor with as little as 1ns of propagation delay.

### 11.2 Typical Application



**Figure 3. RS2G241 Application**

#### 11.2.1 Design Requirements

This device uses CMOS technology and has balanced output drive. Take care to avoid bus contention because it can drive currents that would exceed maximum limits. The high drive also creates fast edges into light loads, so routing and load conditions must be considered to prevent ringing.

#### 11.2.2 Detailed Design Procedure

##### 1. Recommended Input Conditions

- Rise time and fall time specs. See ( $\Delta t/\Delta V$ ) in Recommended Operating Conditions.
- Specified high and low levels. See ( $V_{IH}$  and  $V_{IL}$ ) in Recommended Operating Conditions.
- Inputs are overvoltage tolerant allowing them to go as high as ( $V_I$  max) in Recommended Operating Conditions at any valid  $V_{CC}$ .

##### 2. Recommend Output Conditions

- Load currents must not exceed ( $I_O$  max) per output and must not exceed (Continuous current through  $V_{CC}$  or GND) total current for the part. These limits are located in Absolute Maximum Ratings.
- Outputs must not be pulled above  $V_{CC}$  during normal operation or 5.5 V in high-z state.

## 12 POWER SUPPLY RECOMMENDATIONS

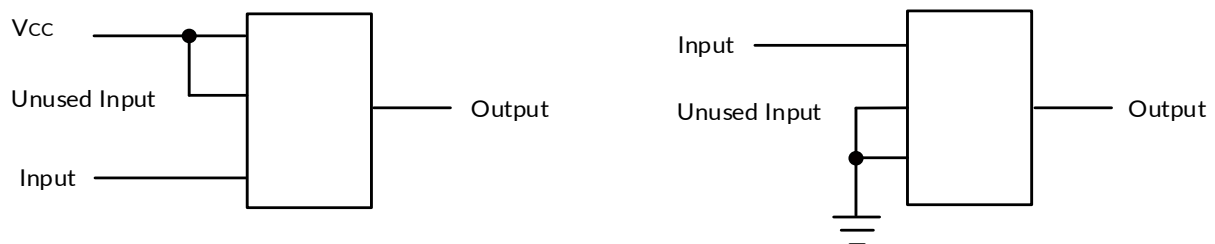
The power supply pin should have a good bypass capacitor to prevent power disturbance. For devices with a single supply, a 0.1 $\mu$ F capacitor is recommended and if there are multiple  $V_{CC}$  terminals then 0.01 $\mu$ F or 0.022 $\mu$ F capacitors are recommended for each power terminal. It is acceptable to parallel multiple bypass caps to reject different frequencies of noise. The 0.1 $\mu$ F and 1 $\mu$ F capacitors are commonly used in parallel. The bypass capacitor should be installed as close to the power terminal as possible.

## 13 LAYOUT

### 13.1 Layout Guidelines

When using multiple bit logic devices inputs should not ever float. In many cases, functions or parts of functions of digital logic devices are unused; for example, when only two inputs of a triple-input AND gate are used or only 3 of the 4 buffer gates are used. Such input pins should not be left unconnected because the undefined voltages at the outside connections result in undefined operational states. Specified below are the rules that must be observed under all circumstances. All unused inputs of digital logic devices must be connected to a high or low bias to prevent them from floating. The logic level that should be applied to any particular unused input depends on the function of the device. Generally, they will be tied to GND or  $V_{CC}$  whichever make more sense or is more convenient.

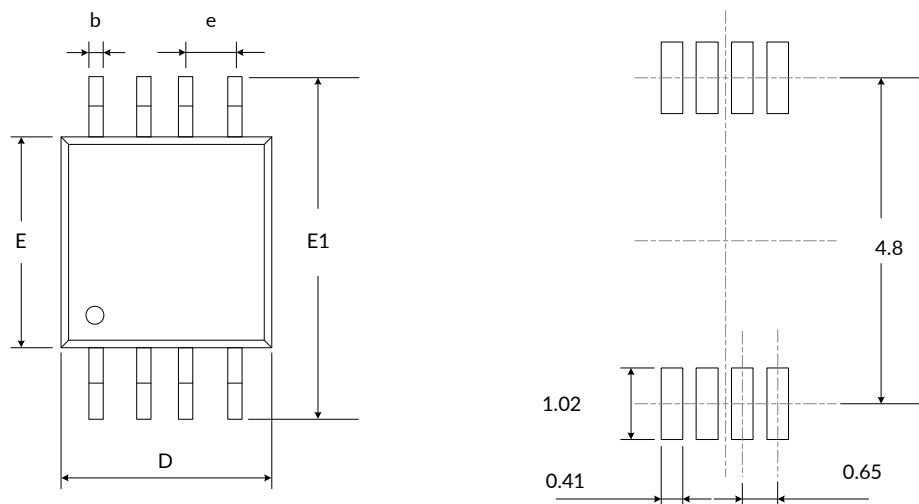
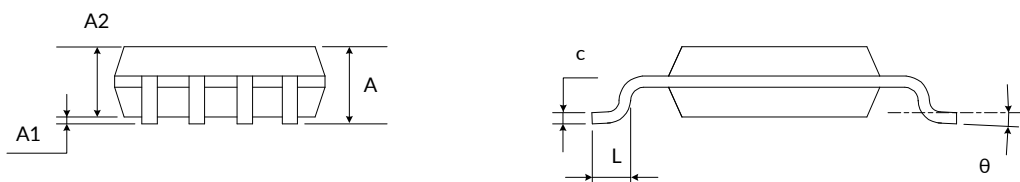
### 13.2 Layout Example



**Figure 4. Layout Diagram**

# 14 PACKAGE OUTLINE DIMENSIONS

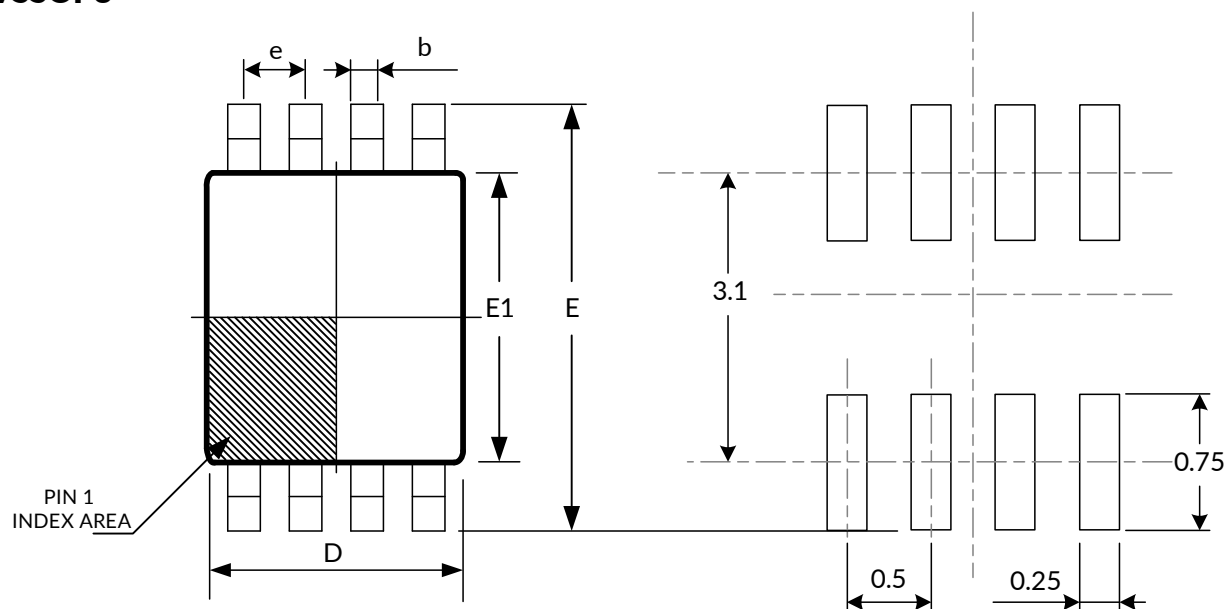
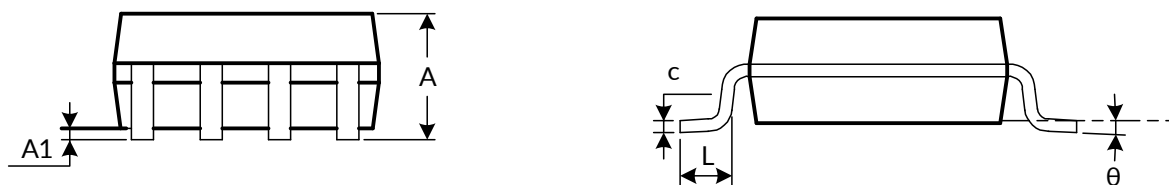
## MSOP8<sup>(3)</sup>


**RECOMMENDED LAND PATTERN (Unit: mm)**


Symbol	Dimensions In Millimeters		Dimensions In Inches	
	Min	Max	Min	Max
A <sup>(1)</sup>	0.820	1.100	0.032	0.043
A1	0.020	0.150	0.001	0.006
A2	0.750	0.950	0.030	0.037
b	0.250	0.380	0.010	0.015
c	0.090	0.230	0.004	0.009
D <sup>(1)</sup>	2.900	3.100	0.114	0.122
e	0.650(BSC) <sup>(2)</sup>		0.026(BSC) <sup>(2)</sup>	
E <sup>(1)</sup>	2.900	3.100	0.114	0.122
E1	4.750	5.050	0.187	0.199
L	0.400	0.800	0.016	0.031
$\theta$	0°	6°	0°	6°

**NOTE:**

1. Plastic or metal protrusions of 0.15mm maximum per side are not included.
2. BSC (Basic Spacing between Centers), "Basic" spacing is nominal.
3. This drawing is subject to change without notice.

**VSSOP8 (3)**

**RECOMMENDED LAND PATTERN (Unit: mm)**


Symbol	Dimensions In Millimeters		Dimensions In Inches	
	Min	Max	Min	Max
A <sup>(1)</sup>	0.600	0.900	0.024	0.085
A1	0.000	0.100	0.000	0.004
b	0.170	0.250	0.007	0.010
c	0.100	0.200	0.004	0.008
D <sup>(1)</sup>	1.900	2.100	0.075	0.083
e	0.500 (BSC) <sup>(2)</sup>		0.020 (BSC) <sup>(2)</sup>	
E	3.000	3.200	0.118	0.126
E1 <sup>(1)</sup>	2.200	2.400	0.087	0.095
L	0.200	0.350	0.008	0.014
$\theta$	0°	6°	0°	6°

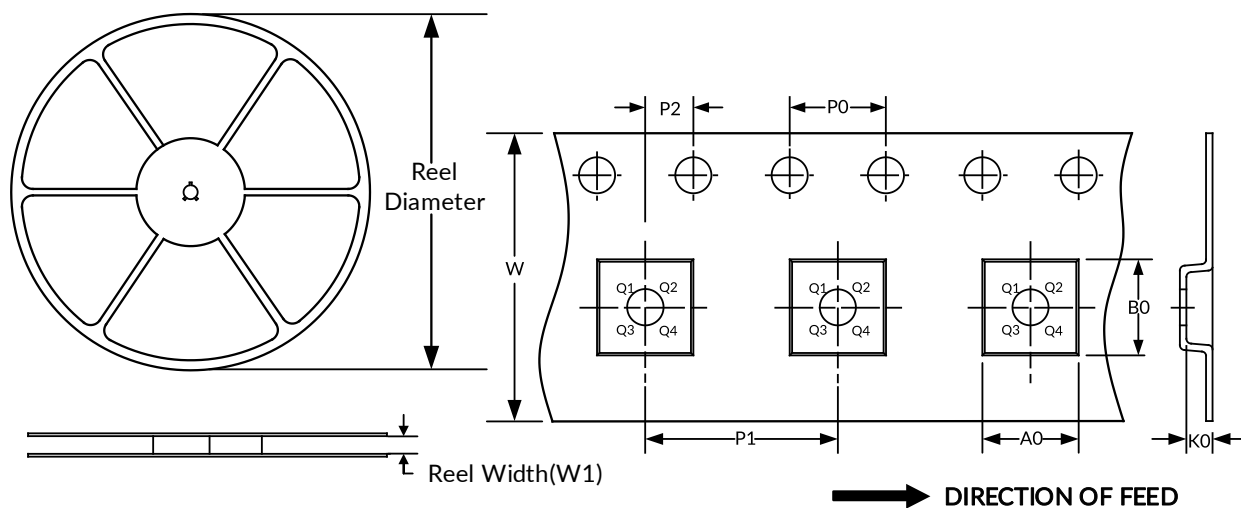
**NOTE:**

1. Plastic or metal protrusions of 0.15mm maximum per side are not included.
2. BSC (Basic Spacing between Centers), "Basic" spacing is nominal.
3. This drawing is subject to change without notice.

# 15 TAPE AND REEL INFORMATION

## REEL DIMENSIONS

## TAPE DIMENSION



NOTE: The picture is only for reference. Please make the object as the standard.

### KEY PARAMETER LIST OF TAPE AND REEL

Package Type	Reel Diameter	Reel Width (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P0 (mm)	P1 (mm)	P2 (mm)	W (mm)	Pin1 Quadrant
MSOP8	13"	12.4	5.20	3.30	1.50	4.0	8.0	2.0	12.0	Q1
VSSOP8	7"	9.5	2.25	3.35	1.40	4.0	4.0	2.0	8.0	Q3

NOTE:

1. All dimensions are nominal.
2. Plastic or metal protrusions of 0.15mm maximum per side are not included.



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